# Beth-like definability results, proof-theoretically

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September  $13<sup>th</sup>$  2024, Proof society workshop

## Beth definability theorem

### Beth definability

Let  $\varphi(R)$  be an FO formula over  $\Sigma \uplus \{R\}$ 

If  $\varphi(R)$  implicitly defines R, that is

$$
\varphi(R) \land \varphi(R') \implies \forall \vec{x}. \ R(\vec{x}) \Longleftrightarrow R'(\vec{x})
$$

then there is a corresponding explicit FO definition for R. That is, we have an FO formula  $\psi(\vec{x})$  over  $\Sigma$  such that

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$$

- Model-theoretic proof using amalgamation
- Proof-theoretic effective proof using interpolation

# Craig interpolation



### Craig interpolation

If  $\varphi \Rightarrow \psi$ , there exists  $\theta$  such that

$$
\varphi \Rightarrow \theta \qquad \text{and} \qquad \theta \Rightarrow \psi
$$

Further,  $\theta$  mentions *only* variables/relation symbols common to  $\varphi$  and  $\psi$ .

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• Robust result

 $\Delta_0$ , intuitionistic/linear logic...

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Further,  $\theta$  mentions *only* variables/relation symbols common to  $\varphi$  and  $\psi$ .

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 $\Delta_0$ , intuitionistic/linear logic...

• An actual *factorization* of proofs  $[Cubrić 94, Saurin 24]$ 

• computable in  $\mathcal{O}(n)$  from cut-free proofs

### Beth definability from interpolation

Fix an implicit definition  $\varphi(R)$ . Since  $\varphi(R)$  determines R, we have

$$
\varphi(R) \land \varphi(R') \implies \forall \vec{x}. \ R(\vec{x}) \Longleftrightarrow R'(\vec{x})
$$

which implies that we have a proof of

$$
\varphi(R) \land R(\vec{x}) \quad \vdash \quad \varphi(R') \Longrightarrow R'(\vec{x})
$$

Applying interpolation we get  $\theta(\vec{x})$  that defines R since we have

$$
\varphi(R) \wedge R(\vec{x}) \vdash \theta(\vec{x}) \text{ and } \theta(\vec{x}) \wedge \varphi(R) \vdash R(\vec{x})
$$

FO formulas  $\psi(\vec{x})$  can be regarded as *queries* 

- regard a relation as a table of elements
- $\psi(\vec{x})$  returns a new table



Correspondence with (a fragment of) SQL

Restrict that to bounded quantifications.

### Our work

Extending this to the nested relational model.

- Led us to known definability results...
- ... but what about effectivity (and efficiency)?

#### Plan

- 1. The setting of nested set
- 2. Extraction of nested definition
- 3. Effective relative rigid categoricity?

# <span id="page-9-0"></span>[The nested relational model, logic](#page-9-0) [and NRC](#page-9-0)

## The nested relational model

We work with **typed objects** 

Types for nested collections

```
T, U ::= \mathfrak{U} \mid \mathsf{Set}(T) \mid 1 \mid T \times U
```
Obvious semantics  $\llbracket T \rrbracket$  determined inductively by  $\llbracket \mathfrak{U} \rrbracket$ .

### Examples

```
Taking \|\mathfrak{U}\| = string, we have
         {((\text{``seagull''}, \text{``gwylan''}), (\text{``goats''}, \text{``geifr''}), \ldots)}\in \mathbb{S}\text{et}(\mathfrak{U}\times\mathfrak{U})\{(\{\text{``shwmae''}, \text{``helo''}\}, \{\text{``hi''}\}), \ldots\}\in \mathcal{S}et(Set(\mathfrak{U}) \times Set(\mathfrak{U})]
         ((), \emptyset, "4", \{ "1", "3" \})\epsilon \in [1 \times \mathsf{Set}(\mathsf{Set}(1)) \times \mathfrak{U} \times \mathsf{Set}(\mathfrak{U})]
```
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         ((), \emptyset, "4", \{ "1", "3" \})\epsilon \in [1 \times \mathsf{Set}(\mathsf{Set}(1)) \times \mathfrak{U} \times \mathsf{Set}(\mathfrak{U})]
```
Usual relational model: only tuples of relations (sets of tuples)

#### Types for nested collections

$$
T, U ::= \mathfrak{U} \mid \mathsf{Set}(T) \mid 1 \mid T \times U
$$

# A transformation of nested sets is a function  $T \to U$  $\rightarrow$  is **not** part of the type system

# A transformation of flat relations

Pre-image of a relation R

$$
\begin{array}{rcl}\n\text{fib}: & \mathsf{Set}(\mathfrak{U}) \times \mathsf{Set}(\mathfrak{U} \times \mathfrak{U}) \quad \to \quad \mathsf{Set}(\mathfrak{U}) \\
(A, R) & \mapsto \quad R^{-1}(A) = \{x \mid \exists y \in A.(x, y) \in R\}\n\end{array}
$$



$$
T,U ::= \mathfrak{U} \mid \mathsf{Set}(T) \mid 1 \mid T \times U
$$

### Transformations of nested collections

Collect all pre-images of individual elements

$$
\begin{array}{rcl}\n\text{fibs}: & \mathsf{Set}(\mathfrak{U} \times \mathfrak{U}) & \rightarrow & \mathsf{Set}(\mathfrak{U} \times \mathsf{Set}(\mathfrak{U})) \\
R & \mapsto & \{(a, \mathsf{fib}(\{a\}, R)) \mid a \in \mathsf{cod}(R)\}\n\end{array}
$$

Collect all susbsets of the input

$$
\begin{array}{rcl}\n\mathcal{P}: & \mathsf{Set}(\mathfrak{U}) & \to & \mathsf{Set}(\mathsf{Set}(\mathfrak{U})) \\
X & \mapsto & \{y \mid y \subseteq X\} \n\end{array}
$$

Note:  $P$  is computationally hard on finite instances

Queries can be specified in multi-sorted first-order logic:

- variables explicitly typed  $x : T$
- basic predicates  $x \in_T z$  and  $x =_T y$   $x, y : T$  and  $z : Set(T)$
- terms for tupling and projections

e.g.,  $\pi_1(((x, z),)))$  :  $(T \times \text{Set}(T)) \times 1$ 

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e.g.,  $\pi_1(((x, z),))) : (T \times \text{Set}(T)) \times 1$ 

# Consider formulas with only bounded quantifications

### $\Delta$ <sup>0</sup> formulas

$$
\varphi,\psi \ \ ::= \ \ t =_T u \mid t \in_T u \mid \forall x \in t \ \varphi \mid \varphi \wedge \psi \mid \neg \varphi
$$

# Examples

# $\Delta_0$  formulas

$$
\varphi,\psi \ \ ::= \ \ t =_T u \mid t \in_T u \mid \forall x \in t \ \varphi \mid \varphi \wedge \psi \mid \neg \varphi
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# Examples

### $\Delta_0$  formulas

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$$

# $\varphi_{\text{fib}}(A, R, X)$  for  $X = R^{-1}(A)$

• Every  $x \in X$  is related to some  $a \in A$ 

 $\forall x \in X. \exists a \in A. \ (x, a) \in R$ 

• For every  $(x, y) \in R$ , if  $y \in A$ , then  $x \in X$ 

 $\forall p \in R$ .  $\pi_2(p) \in A \Rightarrow \pi_1(p) \in X$ 

# Examples

### $\Delta_0$  formulas

$$
\varphi, \psi \ \ ::= \ t =_T u \mid t \in_T u \mid \forall x \in t \ \varphi \mid \varphi \wedge \psi \mid \neg \varphi
$$

# $\varphi_{\mathsf{fibs}}(R, O) \;\mathbf{for}\; O = \{(a, R^{-1}(\{a\})) \; | \; a \in \mathsf{cod}(R)\}$

• For every  $(x, a) \in R$ , there is some  $(a, X) \in O$  s.t.  $x \in X$ 

$$
\forall p \in R. \exists q \in O. \ \pi_1(p) \in \pi_2(O)
$$

• Every element of  $(a, X) \in O$  satisfies  $\varphi_{\text{fib}}(\{a\}, R, X)$ 

$$
\forall q \in O. \quad \forall x \in \pi_2(q). (x, \pi_1(q)) \in R \land \n\forall p \in R. \ \pi_2(p) = \pi_1(q) \Rightarrow \pi_1(p) \in \pi_2(q)
$$

Usual terms and rules for variables, tupling, projections plus the following set operators:

$$
\begin{array}{ll}\n\Gamma \vdash e : T \\
\hline\n\Gamma \vdash \{e\} : \mathsf{Set}(T) & \Gamma \vdash e_1 : \mathsf{Set}(T_1) & \Gamma, \ x : T_1 \vdash e_2 : \mathsf{Set}(T_2) \\
\hline\n\Gamma \vdash \{e\} : \mathsf{Set}(T) & \Gamma \vdash e_1 : \mathsf{Set}(T) & \Gamma \vdash e_2 : \mathsf{Set}(T) \\
\hline\n\Gamma \vdash \emptyset_T : \mathsf{Set}(T) & \Gamma \vdash e_2 : \mathsf{Set}(T) & \Gamma \vdash e_1 \cup e_2 : \mathsf{Set}(T) \\
\hline\n\Gamma \vdash e_1 : \mathsf{Set}(T) & \Gamma \vdash e_2 : \mathsf{Set}(T) & \Gamma \vdash e_1 \setminus e_2 : \mathsf{Set}(T)\n\end{array}
$$

# Explicit definitions: the nested relational calculus (NRC) + Get

Usual terms and rules for variables, tupling, projections plus the following set operators:

$$
\cfrac{\Gamma \vdash e : T}{\Gamma \vdash \{e\} : \mathsf{Set}(T)} \qquad \cfrac{\Gamma \vdash e_1 : \mathsf{Set}(T_1) \qquad \Gamma, \ x : T_1 \vdash e_2 : \mathsf{Set}(T_2)}{\Gamma \vdash \bigcup \{e_2 \mid x \in e_1\} : \mathsf{Set}(T_2)}
$$
\n
$$
\cfrac{\Gamma \vdash e_1 : \mathsf{Set}(T)}{\Gamma \vdash \emptyset_T : \mathsf{Set}(T)} \qquad \cfrac{\Gamma \vdash e_1 : \mathsf{Set}(T)}{\Gamma \vdash e_1 \cup e_2 : \mathsf{Set}(T)}
$$
\n
$$
\cfrac{\Gamma \vdash e_1 : \mathsf{Set}(T)}{\Gamma \vdash e_1 \setminus e_2 : \mathsf{Set}(T)} \qquad \cfrac{\Gamma \vdash e : \mathsf{Set}(T)}{\Gamma \vdash \mathsf{Get}(e) : T}
$$

# Expressiveness of NRC

### Our running examples

- $\bullet$   $(A, R) \mapsto \bigcup \{\textsf{case}(\pi_2(p) \in \mathfrak{U} A, \{\pi_1(p)\}, \emptyset) \mid p \in R\}$
- $R \mapsto \bigcup \{ \{\text{fib}(x, R)\} \mid x \in \{\pi_1(p) \mid p \in R \} \}$

Derivable constructs:

- maps  $\{e_1(x) | x \in e_2\}$
- at type-level,  $Bool := Set(1)$
- basic predicates  $=\tau: T \times T \to$  Bool,  $\in_T: T \times$  Set $(T) \to$  Bool
- case analyses

# Expressiveness of NRC

### Our running examples

- $\bullet$   $(A, R) \mapsto \bigcup \{\textsf{case}(\pi_2(p) \in \mathfrak{U} A, \{\pi_1(p)\}, \emptyset) \mid p \in R\}$
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Derivable constructs:

- maps  $\{e_1(x) \mid x \in e_2\}$
- at type-level,  $Bool := Set(1)$
- basic predicates  $=_T : T \times T \to \text{Bool}$ ,  $\in_T : T \times \text{Set}(T) \to \text{Bool}$
- case analyses
- $\Delta_0$ -separation  $\{x \in e \mid \varphi(x)\}\$

### Proposition

NRC terms  $e: T \to \mathsf{Bool}$  correspond to  $\Delta_0$  formulas  $\varphi(x^T)$ 

### Limits to the expressiveness of NRC

For practical purposes, NRC is not too expressive

- NRC is *conservative* over idealized SQL i.e., for flat queries
- queries *polytime* computable (over finite inputs)

#### **Consequences**

- rules out  $x \mapsto \mathcal{P}(x)$
- cannot represent function spaces with Set(−)

```
Consider (x, y) \mapsto \mathtt{tt}
```

$$
[T \to \mathsf{Set}(U)] \not\simeq [T \times U \to \mathsf{Bool}]
$$

 $[T \to \mathsf{Set}(U)] \hookrightarrow [T \times U \to \mathsf{Bool}]$ 

(For the rest of the talk: no finiteness assumptions)

# <span id="page-24-0"></span>[Extraction from](#page-24-0)  $\Delta_0$  specifications

Recall that  $\varphi(i, o)$  is an implicit definition when it is functional:  $\varphi(i, o) \land \varphi(i, o') \implies o = o'$ 

#### Extraction from  $\Delta_0$  implicit definitions

For every such  $\varphi(i, o)$ , there is a compatible NRC term  $e(i)$ 

$$
\varphi(i, o) \implies o = e(i)
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 $e(i)$  polytime computable from a **focused** proof

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• Extension of Beth definability for flat queries  $\mathsf{Set}(\mathfrak{U}^k) \times \ldots \times \mathsf{Set}(\mathfrak{U}^m) \to \mathsf{Set}(\mathfrak{U}^n)$ 

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- Extension of Beth definability for flat queries  $\mathsf{Set}(\mathfrak{U}^k) \times \ldots \times \mathsf{Set}(\mathfrak{U}^m) \to \mathsf{Set}(\mathfrak{U}^n)$
- Remark: a non-effective proof would still yield an algorithm
	- Can be proven elementarily
	- Alternatively, this can be reduced to a  $\Pi_2^0$  statement

A normal form for proofs refining cut-freeness (Andreoli 90s)

### Rough idea

Decompose proofs by forcing saturations by certain rules in positive and negative phases. Roughly:

- Negative: apply invertible rules as much as possible
- Positive: focus on a single formula until it turns negative.

A normal form for proofs refining cut-freeness (Andreoli 90s)

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- Negative: apply invertible rules as much as possible
- Positive: focus on a single formula until it turns negative.

### Complexity-wise (to the best of my knowledge)

A cut-free proof can be turned into a focused cut-free proof in exponential time.

### Toward a proof system for nested sets

Wlog, we restrict to the following syntax

t,  $u$  ::=  $x | (t, u) | \pi_1(t) | \pi_2(t) | ()$ 

 $\varphi, \psi \ ::= \ t = \mathfrak{U} \ u \mid t \neq \mathfrak{U} \ u \mid \exists x \in \mathcal{T} \ t \ \varphi \mid \forall x \in \mathcal{T} \ t \ \varphi \mid \varphi \wedge \psi \mid \varphi \vee \psi$ 

### Toward a proof system for nested sets

Wlog, we restrict to the following syntax t,  $u$  ::=  $x | (t, u) | \pi_1(t) | \pi_2(t) | ()$  $\varphi, \psi \ ::= \ t = \mu \ u \mid t \neq_{\mathfrak{U}} u \mid \exists x \in_T t \ \varphi \mid \forall x \in_T t \ \varphi \mid \varphi \land \psi \mid \varphi \lor \psi$ 



# Toward a proof system for nested sets

Wlog, we restrict to the following syntax  $t, u$  ::=  $x | (t, u) | \pi_1(t) | \pi_2(t) | ()$  $\varphi, \psi \ ::= \ t = \sup u \mid t \neq_{\Omega} u \mid \exists x \in_T t \varphi \mid \forall x \in_T t \varphi \mid \varphi \wedge \psi \mid \varphi \vee \psi$ 



- Bakes the axiom of extensionality in the definition of  $=\tau$
- No further non-equational axioms
- For the rest of the talk: we use sequent calculus

### Formal proofs of functionality

Certificate that  $\varphi(i, o)$  is an implicit definition: a derivation

$$
\cdot; \; \varphi(i, o), \; \varphi(i, o') \vdash o = o'
$$

$$
\frac{ax - z = 0, x \in X, z \in x; z \in o' + z \in o' \quad (7)}{z \in o, x \in X, z \in x; \chi(X, x, z), \chi(X, x, z) \Rightarrow z \in o' + z \in o' \quad (6)}
$$
\n
$$
= \text{snsm}
$$
\n
$$
\frac{v \cdot L \quad z \in o, x \in X, z \in x; \chi(X, x, z), \chi(X, x, z) \Rightarrow z \in o' + z \in o' \quad (5)}
$$
\n
$$
\frac{z \in o, x \in X, z \in x; \chi(X, x, z), \chi(a \in x (\chi(X, x, a)) \Rightarrow a \in o') + z \in o' \quad (6)}
$$
\n
$$
\frac{z \in o, x \in X, z' \in x; z = qz', \chi(X, x, z), \forall a \in x (\chi(X, x, a) \Rightarrow a \in o') + z \in o'}{v \cdot L \quad z \in o, x \in X; \psi(X, x, z), \forall a \in x (\chi(X, x, a) \Rightarrow a \in o') + z \in o' \quad (4)}
$$
\n
$$
\frac{z \in o, x \in X; \psi(X, x, z), \forall a \in x (\chi(X, x, a) \Rightarrow a \in o') + z \in o'}{v \cdot L \quad z \in o, x \in X; \psi(X, x, z), \forall y \in X \forall a \in y (\chi(X, y, a) \Rightarrow a \in o') + z \in o' \quad (9)}
$$
\n
$$
\frac{z \cdot b \cdot x \in X; \psi(X, x, z), \Sigma(X, o') + z \in o'}{z \in o; \exists x \in X \psi(X, x, z), \Sigma(X, o') + z \in o' \quad (9)}
$$
\n
$$
\frac{z \cdot b \cdot x \in X; \psi(X, x, z), \Sigma(X, o') + z \in o'}{z \cdot L \quad z \in o; \Sigma(X, o), \Sigma(X, o') + z \in o' \quad (9)}
$$
\n
$$
\frac{z \cdot z \cdot \Sigma(X, o), \Sigma(X, o') + z \in o'}{z \cdot K \quad (2 \times 0, \Sigma(X, o') + o \subseteq o' \quad (0)}
$$
\n
$$
\frac{z \cdot z \cdot \Sigma(X, o), \Sigma(X, o') + z \in o'}{z \cdot K \quad (2 \times 0, \Sigma(X, o') + o' \in o
$$

Problem: what inductive invariant?

### The intuitionistic case



Input:  $\Gamma(c, l), \Delta(c, r) \vdash \psi$ , cut-free Output: a NRC term  $e(c)$  s.t.

# Key lemma • if  $\psi$  is  $l = r$ , then  $\Gamma, \Delta \models l = e \wedge r = e$

• if  $\psi$  is  $l \subset r$ , then  $\Gamma, \Delta \models l \subseteq e \wedge e \subseteq r$ 

• if 
$$
\psi
$$
 is  $l \in r$ , then  
\n $\Gamma, \Delta \models l \in e$
### The intuitionistic case



Input:  $\Gamma(c, l), \Delta(c, r) \vdash \psi$ , cut-free Output: a NRC term  $e(c)$  s.t.

# Key lemma • if  $\psi$  is  $l = r$ , then  $\Gamma, \Delta \models l = e \wedge r = e$ • if  $\psi$  is  $l \subset r$ , then  $\Gamma, \Delta \models l \subseteq e \land e \subseteq r$ • if  $\psi$  is  $l \in r$ , then  $\Gamma, \Delta \models l \in e$

Why this is easy: single RHS formula, subformula of  $=\tau$ .

Let us look at the key step that involves interpolation.

$$
\frac{\Gamma, z \in_T l, \Delta \vdash z \in_T r}{\Gamma, \Delta \vdash l \subseteq_T r} \qquad \longrightarrow \qquad \frac{\Gamma, z \in_T l, \Delta \models z \in_T e^{\text{IH}}}{\Gamma, \Delta \models l \subseteq_T e \land e \subseteq_T r}
$$

Assuming a  $\Delta_0$  interpolant  $\theta(z)$  such that

 $\Gamma \wedge z \in_T l \models \theta(z)$  and  $\theta(z) \models \Delta \Rightarrow z \in_T r$ 

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we can set  $e := \{x \in e^{\text{IH}} \mid \theta(z)\}\$ 

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$$

Assuming a  $\Delta_0$  interpolant  $\theta(z)$  such that

 $\Gamma \wedge z \in \negthinspace r \, l \models \theta(z)$  and  $\theta(z) \models \Delta \Rightarrow z \in \negthinspace r \, r$ 

we can set  $e := \{x \in e^{\text{IH}} \mid \theta(z)\}\$ 

Other key cases in a hurry ∪ for  $\vee$ -L,  $\bigcup$  for  $\forall$ -L,  $\{-\}$  for  $\exists$ -R Difficulty: with classical logic, we can contract the goal formula

Reduction to the  $\in$  case From a proof  $\Gamma, \Delta \vdash \exists x \in^+ r. l = x$ , compute a NRC term e such that  $l \in e$ 

• Weaker than definability: **set** of possible solutions

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- Weaker than definability: **set** of possible solutions
- Proven by outer induction on the type structure
- Set-case by modifying the input proof to

$$
\exists x \in_{\mathsf{Set}(T)} \exists c \in a. \ c \in l \Leftrightarrow c \in x \qquad (\text{fresh } a)
$$

and then applying interpolation

Working with multisorted FO, no function symbols, signatures L, R and  $C \subseteq L \cap R$ . (and C "has a sort with  $\geq 2$  elements")

#### Theorem

If we have a focused derivation of

$$
\Gamma, \Delta \vdash \exists r. \forall c. \ \lambda(c) \Longleftrightarrow \rho(r, c)
$$

then we can compute in linear time a  $\psi(\vec{p}, c)$  over C such that

$$
\Gamma, \Delta \models \exists \vec{p}.\forall c. \ \lambda(c) \Longleftrightarrow \psi(\vec{p}, c)
$$

Call  $\psi$  a **parameterized definition** for  $\lambda$ .

#### Reminder of what is the theorem

 $\Gamma, \Delta \vdash \exists r. \forall c. \ \lambda(c) \Longleftrightarrow \rho(r, c)$  $\psi$  such that  $\Gamma, \Delta \models \exists \vec{p}.\forall c. \lambda(c) \Longleftrightarrow \psi(\vec{p}, c)$ 

(Not useful) ways to instantiate the hypotheses:

- Trivial  $\exists r$ .: same premise as in Beth definability
- One generalization  $\varphi(R)$  defines finitely many Rs, then we have a parameterized definition of R
	- Throw in a finite sort *n* to index finitely many distinct  $R_i$ with  $\varphi(R_i)$  for all i and  $\varphi(R)$
	- (Kueker already gave a proof-theoretic method)

## Relation to Beth definability/vague examples (2/2)

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An instantiation (of questionable utility?):

- Fix a FO formula  $\varphi(P)$  over a signature  $\Sigma \uplus \{P\}$
- Call CA the theory of comprehension over  $\Sigma$
- If we have

$$
\varphi(P), \mathsf{CA} \vdash \exists X. \ \forall x. \ P(x) \Leftrightarrow x \in X
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then P is parametrically FO-definable over  $\Sigma$ .

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• Can be derived from a theorem of Chang & Makkai

### Parametrized definability from countably many options

Extends the cardinality condition of Kueker as far as possible.

Theorem (Chang-Makkai, 64)

Let  $\mathcal T$  be a theory over  $\Sigma \cup \{P\}$ . TFAE:

- P is parametrically FO-definable over  $\Sigma$  (in  $\mathcal{T}$ )
- for every model  $(M, \ldots, P)$  of  $\mathcal T$  there are at most  $|M|$ many valid alternatives for P (i.e.  $P' \subseteq M$  such that  $(M, \ldots, P')$  is also a model of  $\mathcal{T}$ )

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(equivalent condition: there exists a saturated model. . . )

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#### Question

Can we give a satisfactory effective counterpart to this?

#### Back to our nested relations business

Adaptation in our setting with  $\Delta_0$  set-theoretic formulas

(sadly not derived as a corollary)

#### Theorem

If we have a focused derivation

$$
\Gamma(\vec{i},...),\Delta(\vec{i},r,...)\vdash \exists r'\in r.\forall x\in a.\ \lambda(x,...)\Longleftrightarrow \rho(r',...,x)
$$

then we have in linear time a NRC term  $E(\vec{i})$  such that

$$
\Gamma(\vec{i},...), \Delta(\vec{i},r,...) \models a \cap \lambda \in E(\vec{i})
$$

Proof: induction; we need also to compute a  $\theta(\vec{i})$  such that

$$
\Delta(\vec{i},r,\ldots) \models \theta(\vec{i}) \quad \text{and} \quad \Gamma(\vec{i},\ldots),\theta(\vec{i}) \models a \cap \lambda \in E(\vec{i})
$$

#### Key step: existential rule introducing the "main" formula

With 
$$
\mathcal{G} = \exists r' \in^+ r.\forall z \in c. \quad \lambda(z) \iff \rho(z, r')
$$

$$
\vee \frac{\Theta_L, \Theta_R, x \in c \vdash \Delta_L, \Delta_R, \neg \rho(x, w), \lambda(x), \mathcal{G}}{\wedge \frac{\Theta_L, \Theta_R, x \in c \vdash \Delta_L, \Delta_R, \rho(x, w) \Rightarrow \lambda(x), \mathcal{G}}{\forall \frac{\Theta_L, \Theta_R, x \in c \vdash \Delta_L, \Delta_R, \lambda(x) \Leftrightarrow \rho(x, w), \mathcal{G}}{\exists^+ \frac{\Theta_L, \Theta_R \vdash \Delta_L, \Delta_R, \forall z \in c. (\lambda(z) \Leftrightarrow \rho(z, w)), \mathcal{G}}{\Theta_L, \Theta_R \vdash \Delta_L, \Delta_R, \mathcal{G}}}
$$

- Shape around the root of the tree guaranteed by focusing
- Applying the induction hypothesis we have

$$
\Theta_L, x \in c \models \lambda(x), \Delta_L, \theta_1^{\mathsf{IH}} \lor \Lambda \in E_1^{\mathsf{IH}}
$$

$$
\Theta_R \models \neg \rho(x, w), \Delta_R, \neg \theta_1^{\mathsf{IH}}
$$

• Take 
$$
\theta := \exists x \in c. \ \theta_1^{\text{IH}} \wedge \theta_2^{\text{IH}}
$$
 and  

$$
E := \left\{ \left\{ x \in c \mid \theta_2^{\text{IH}} \right\} \right\} \ \cup \ \bigcup \left\{ E_1^{\text{IH}} \cup E_2^{\text{IH}} \mid x \in c \right\}
$$

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. . .

### What have we not learned?

#### Extraction from  $\Delta_0$  implicit definitions

For every such  $\varphi(i, o)$ , there is a compatible NRC term  $e(i)$ 

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\varphi(i, o) \implies o = e(i)
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 $e(i)$  polytime computable from a **focused** proof

• The intuitionistic case is much easier

#### Conservativity for implicit definitions

If  $\phi(i, o)$  is functional, then there is a formula  $\chi(\vec{x})$  such that the conjoined formula  $\phi^{-1}(i, o) \wedge \forall \vec{x}$ .  $\chi(\vec{x}) \vee \neg \chi(\vec{x})$  can be proved to be functional in intuitionistic logic.

- (but finding  $\chi$  has no reason being easy!)
- W/o the complexity bound: easier proof via model theory

Nested collections can be regarded as multi-sorted structures

An object X of sort  $Set(\mathfrak{U} \times Set(\mathfrak{U}))$ 

Sorts:  $\mathfrak{U}, \mathsf{Set}(\mathfrak{U}), \mathfrak{U} \times \mathsf{Set}(\mathfrak{U})$ 

Function symbols:  $\pi_1, \pi_2, \langle -, - \rangle$ 

Relation symbol:  $\epsilon$ 

**Semantics:** subobjects of X

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- product, disjoint union of structures  $\mathfrak{M}, \mathfrak{N} \mapsto \mathfrak{M} \times \mathfrak{N}, \mathfrak{M} + \mathfrak{N}$
- definable substructures and quotients

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#### NRC and interpretations

For structures corresponding to nested collections, NRC and  $\Delta_0$ -interpretations coincide

#### The key model-theoretic lemma

Consider models of a theory  $\mathcal T$  over two sorts  $\tau$  and  $\sigma$ Multi-sorted implicit definability

*σ* is **implicitly definable from**  $\tau$  when every  $f : \mathfrak{M}|_{\tau} \cong \mathfrak{M}'|_{\tau}$ has a unique extension  $\hat{f}: \mathfrak{M} \cong \mathfrak{M}'$ 



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Lemma ( $\sim$  relative rigid categoricity, dcl)

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**Example:**  $\mathcal{T}$  says that  $\tau$  is a real closed field and that  $\sigma$  is a dimension two field extension with a distinguished  $i$  with  $i^2 = -1.$ 

Lemma ( $\sim$  relative rigid categoricity, dcl)  $\sigma$  implicitly definable from  $\tau \Rightarrow \exists$  interpretation of  $\mathcal T$  into  $\mathcal T|_{\tau}$ .

Example (cont): exercise :)

## **Coordinizability**

### Lemma ( $\sim$  relative rigid categoricity, dcl)

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Proof idea: use Beth definability after computing coordinates.

Coordinizability (∼ Gaifman's coordinizability)

 $\exists$  a FO-definable partial surjection  $\tau^n \to \sigma$ . That is, there exists  $\chi(p^{\vec{\tau}}, x^{\sigma})$  such that  $\forall x.\exists \vec{p}.\ \chi(\vec{p},x)$  $\forall \vec{p} \ x \ y. \ \chi(\vec{p}, x) \wedge \chi(\vec{p}, y) \Longrightarrow x = y$ 

## **Coordinizability**

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From implicit definability: via the omitting type theorem

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Question

Can we make coordinizability effective/efficient?

## Effective implicit definabilty for sorts  $(1/2)$

Problem #1: witness of implicit definability? Multi-sorted implicit definability (mild alteration) *σ* is **implicitly definable from** *τ* if whenever  $\mathfrak{M}|_{\tau} = \mathfrak{M}'|_{\tau}$ , there is a unique isomorphism  $f : \mathfrak{M} \cong \mathfrak{M}'$  with  $f|_{\tau} = id$ .



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Idea to reduce to provability

Consider the theory  $\mathcal{T} \cup \mathcal{T}'$  over  $\tau, \sigma, \sigma'$  talking about the join of a pair of models  $\mathfrak{M} \cup \mathfrak{M}'$ 

## Effective implicit definabilty for sorts  $(2/2)$

#### Lemma

Implicit definability is equivalent to the existence of a FO formula  $\psi(x^{\tau}, y^{\tau'})$  such that

 $\mathcal{T} \cup \mathcal{T}' \vdash \psi$  is an embedding extending the identity

 $(\Rightarrow)$  use Beth definability to compute  $\psi$ !

 $(\Leftarrow)$  FO definable embedding = isomorphism (crucial thing  $\tau \neq \tau'$ !) (requires comprehension for the trivial part  $(ACA'_0)$ )

## We have a nice  $\Pi^0_2$  statement

Effective implicit definable  $\Rightarrow$  coordinizable, effectively

Question: how efficient can we make that?

#### For intuitionistic logic

From a cut-free proof of totality of  $\varphi(x^{\tau}, y^{\tau'})$  in LJ

$$
\vdash \forall x^{\tau} \exists y^{\tau'}.\ \varphi(x,y)
$$

we can compute in polynomial time coordinates for  $\tau$ .

Proof idea: induction until we hit the ∃-R rule

#### Restricted to  $\Sigma_1$  formulas

From a cut-free proof of totality of  $\varphi(x^{\tau}, y^{\tau'})$ , if  $\varphi$  is  $\Sigma_1$  and functional, we can compute coordinates for  $\tau$ .

Proof: via Herbrand's theorem

(and some fiddly steps to get rid of function symbols)

#### For intuitionistic logic

From a cut-free proof of totality of  $\varphi(x^{\tau}, y^{\tau'})$  in LJ we can compute in polynomial time coordinates for  $\tau$ .

While all  $\varphi$  can be "made intuitistically total", I don't have a proof of this that does not presuppose classical coordinizability.

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For NRC,  $\varphi$  exhausts the quantifier hierarchy.

#### Why that won't generalize too well

There exists a silly  $\Pi_2$   $\varphi$  functional and total (but which is not an embedding) such that  $\tau$  is not coordinizable.

Nice theorem about NRC and implicit definitions but:

• Proof-theoretic take on definability results?

(one excuse: complexity)

- 
- 
- Algebraic closures

• Chang-Makkai (∼ countably many predicates) • Definable closures (what I just discussed) Nice theorem about NRC and implicit definitions but:

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## Thanks for listening! :)

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