# **CSCM12: software concepts and efficiency Trees & friends**

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slido.com, code #1426271

# **Logistics**

#### **Coursework 1 feedback released**

• Rather high marks

(up to 6 bonus marks, lenient marking)

- If you do not have 30/30, please pay attention to the feedback
- Overall, fine except the answers to  $4)c$ ) which were often unclear/non-specific

#### **Tomorrow: deadline for coursework 2**

- Official deadline at 11am
- (just let me know if you need a bit of slack, it should be fine, I will leave the submission portal open for a couple of extra hours in case you have technical difficulties)
- I will try to be in the lab tomorrow morning, but otherwise won't be available for support

I released a revision sheet **for the whole module**.

- Should contain **all** of the material you would be reasonably expected to know for the exam
- Based on last year's lecture content
- I would recommend you take a look to check that you know most of the things covered so far **excluding graphs, trees and hash tables/functions**.
- If there is anything unclear, feel free to ask!

# **Today**

Introduce tree-like datastructure

- What are they?
- How to encode them in java?
- Motivating examples & applications

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Also an opportunity to **recap material on sorting algorithms** with heapsort. (c.f. challenge task of last lab)

# **Motivations**

#### **Recursive definition of a list**

A list of *A*s is either

- An empty list
- Or an *A* and (a reference to) another list of *A*s





4 2 37 9







#### **For the most part**

Recursive datatypes with possibly **multiple** subobjects of the same kind



(list-like datatypes are degenerate tree-like datatypes)

Tree-like structures come up in a variety of contexts:

• Efficient datastructures: sets/priority queues with  $\mathcal{O}(\log(n))$  operations, random access lists, quad/octtrees…



Trees can also come up as natual objects we'd like to manipulate

• E.g., anything hierarchical, abstract syntax trees, directory trees



# **Generalities**

## **Recursive mathsy definition of a tree**

#### **Formal definition**

A tree with labels in *L* is a pair (label,  $\langle c_1, \ldots, c_n \rangle$ ) where:

- label *∈ L*
- $\langle c_1, \ldots, c_n \rangle$  is a list of trees with labels in *L* (possibly an empty list)



## **Vocabulary/basic notions**



depth  $\leq$  size  $\leq$  max $(arity)^{\text{depth}}$ 

- $\bullet$  breadth-first enumeration:
- 
- 
- 
- depth-first prefix enumeration:  $\bigcirc$   $\bigcirc$

## **In java**

• Typically encoded via a recursive class

```
class Tree<T>
{
  public T label;
  public ArrayList<Tree<T>> children;
  public static <T> Tree<T> Leaf(T x)
  {
      Tree\leqT> t = new Tree \leq T>( );
      t.children = new ArrayList<Tree<T>>();
      t.label = x;
      return t;
  }
}
```
 $Tree \leq Integer$  root =  $Leaf(9)$ ; root.children.add(Leaf(8)); root.children.add(Leaf(1)); root.children.add(Leaf(2)); Tree<Integer> someNode =  $root.get(1)$ ; someNode.add(Leaf(6)): someNode.get(0).add(Leaf(8));

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## **Tree example with memory representation**

 $Tree \leq Integer$  root = Leaf(10); root.children.add(Leaf(5)); root.children.add(Leaf(11)); root.children.add(Leaf(12)); root.children.get(1).add(Leaf(3));

#### **A somewhat honest of the representation in memory**



### **Non-trees?**

• With linked lists, possible to create **cycles**

(and worse pathologies in the case of doubly-linked lists)

• Same here + an additional pitfall: **sharing**



Not necessarily:

• They can be seen as **graphs**

(Topic of next lecture)

• Can represent (potentially infinite) trees



#### **Cons**

• **Cycles**: no longer a finite well-defined notion of **depth**

*⇒* a lot of tree algorithm no longer terminates like e.g. traversal

• **Sharing**: a single update modifies **several spots** in the unravelling

(*⇒* not an issue for **immutable** datastructures)

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only regular trees, which may arguably admit more convenient representations

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- One just has to be extra clear about what they consider legal inputs/outputs
- **For this lecture:** no more sharing/cycles

## **Tree-like datastructures**

• *. . .*

Often, you may want more/less flexibility than the generic tree datastructure

- Do you want to bound the arity of internal nodes?
- Do you care about the ordering of children?
- Do you care about empty spots for future children?
- Do you want more labels?
- Do you want different type of labels for e.g. leaves?

```
class AST {
  boolean isAnOperand;
  String repr;
  AST lhs;
  AST rhs;
}
```
→ for most situations, similar issues/resolutions 15

**Binary trees** are those trees whose nodes have at most two children.

```
class BTree<T> {
  T label;
  BTree<T> leftChild;
  BTree<T> rightChild;
}
```
Conventions:

• leftChild and rightChild may be set to **null**

(for a leaf: both are **null**)

• it is possible that leftChild = **null** and rightChild != **null**

(we care about the order and "empty spots")

# **Binary search trees**

# **Motivation: set with**  $\mathcal{O}(\log(n))$  **lookup and delete**

...

Set(); // creates an empty set **void** remove(T e); // removes one element **boolean** contains(T e): // do I contain the element? **void** add(T e); // add one element Set union(Set s2); // adds all elements of s2



## **A datastructure to represent set of numbers**

#### **Definition**

A **Binary Search Tree** is a binary tree labeled by integers such that



$$
\Rightarrow \qquad l \leq x \leq r
$$







#### **Look up an element boolean contains(int e)**



# **Complexity of boolean contains(int e)?**



## **Complexity of boolean contains(int e)?**



*→ O*(depth)

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*→ O*(depth)

#### **Relation to the size of the set**

- Best case: the tree is balanced  $\rightarrow$  depth =  $\mathcal{O}(size)$
- Worst case: one child everywhere  $\rightarrow$  depth =  $\Omega$ (size)

*→* **Important concern:** work on **balanced trees**

#### **Insert an element void add(int e)**



#### **Insert an element void add(int e)**



- Complexity: still *O*(depth)
- **Issue:** repeatedly inserting bigger and bigger elements can unbalance a tree

Try inserting 1*,* 2*,* 3*, . . .* to Leaf(0)

# **Solutions (not covered in-depth here)**

- Either try to do some probabilistic analysis and try to prove things are not that bad on average for a given use-case *. . .*
- $\ldots$  or use fancier invariants to have classes of trees with depth =  $\mathcal{O}(\log(\text{size}))$
- Paradigmatic examples: red-black trees and AVLs



- Involved "repair" procedures to maintain the invariants after an insertion/deletion running in *O*(depth)
- Something like this is implemented for TreeSet 22

# **So now, you should be able to tell why this table is like this**



**Priority queues, heaps and heapsort**

## **Quick note**

#### **Motivation**

Implement a priority queue with  $\mathcal{O}(\log(n))$  operations  $+$   $\rightarrow$  a new in-place sorting algorithm in  $\mathcal{O}(n \log(n))$ 

**The two operations supported by a priority queue**

```
void enqueue(T e, int priority);
```
T dequeue();

This material is explained in some details in last week's lab!

- The last task was marked as challenge because it's about trees and we had not covered that last week
- But now you should try to do it!

# **What's a heap?**

#### **Definition**

A min-heap is a binary tree such that

- The label of every node is smaller than its children's
- All of its levels are full, except possibly the last
- The last level is completely filled left-to-right



(for priority queues: numbers are priorities  $+$  extra label type  $\top$  in nodes)

### **Examples/counter-examples**



## **Inserting a new element and repairing in**  $\mathcal{O}(\log(n))$





# **Deleting the root and repairing in**  $\mathcal{O}(\log(n))$



↑ valid heap

#### **Representing trees as arrays**

While the shape of a tree is good ot keep in mind, when they are of bounded arity and close to complete, it might be better to represent them as arrays



- Fast access due to  $\mathcal{O}(1)$  lookup in arrays
- Downsides: *potentially* **wasting memory** and bounding a priori arities

 $(absent nodes = cells filled with **null**)$ 

For heaps: that's a good representation!

## **Heap sort**

#### **The algorithm**

- start with an empty heap
- insert all the elements in the collection you want sorted

 $\sum_{i=1}^{n} K \log(i) + K' = \mathcal{O}(n \log(n))$ 

• insert the value of the root at the back of your output and delete the root

 $\sum_{i=1}^{n} K'' \log(i) + K''' = \mathcal{O}(n \log(n))$ 

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- insert the value of the root at the back of your output and delete the root  $\sum_{i=1}^{n} K'' \log(i) + K''' = \mathcal{O}(n \log(n))$
- Optimal asymptotic complexity for a comparison-based sort!
- Can be done *in-place* in an array wiht minor adjustement

 $O(n)$  space complexity

#### **Bubble sort**

- $\bullet$   $\mathcal{O}(n^2)$
- In-place

# **Quick sort**

- $\bullet$   $\mathcal{O}(n^2)$ ,  $\mathcal{O}(n \log(n))$  on average with randomized pivot
- Easily done in-place for arrays
- $\mathcal{O}(n \log(n))$  with a smart pivot, but this breaks the in-place aspect of the algo.

#### **Merge sort**

- $\mathcal{O}(n \log(n))$ , good for parallelization
- Not in-place for arrays
- A *stable* sort (does not disturb elements that are "equal")

# **Heap sort**

- $\bullet$   $\mathcal{O}(n \log(n))$
- In-place!

# **CountSort**

• Not a comparison-based sort, can run in linear time **if working with numbers in a restricted range**.

# **That's all for today**

See you in the lab to practice working with trees!

Next time we will introduces **graphs**.

