CSCM12: software concepts and efficiency Trees & friends

Cécilia Pradic March 13th 2023

- Friday and next Monday: unless I announce otherwise, I am on strike and Tonicha won't be there either
- Like last time, I will merely point at a list of exercises in the books that you might want to look at
- Feel free to come say hello on the picket line
- But otherwise, also feel free to progress on the labs and coursework.

Today

Introduce tree-like datastructure

- What are they?
- How to encode them in java?
- Motivating examples & applications

Today

Introduce tree-like datastructure

- What are they?
- How to encode them in java?
- Motivating examples & applications

Also an opportunity to **recap material on sorting algorithms** with heapsort. (c.f. challenge task of last lab)

Motivations

Recursive definition of a list

A list of As is either

- An empty list
- Or an *A* and (a reference to) another list of *A*s



Recursive definition of a list	
A list of <i>A</i> s is either	
• An empty list	
• Or an <i>A</i> and (a reference to) another list of <i>A</i> s	\leftarrow one subobject of the same kind







(list-like datatypes are degenerate tree-like datatypes)

Tree-like structures come up in a variety of contexts:

• Efficient datastructures: sets/priority queues with $O(\log(n))$ operations, random access lists, quad/octtrees...



Trees can also come up as natual objects we'd like to manipulate

• E.g., anything hierarchical, abstract syntax trees, directory trees



Generalities

Recursive mathsy definition of a tree

Formal definition

A tree with labels in *L* is a pair (label, $\langle c_1, \ldots, c_n \rangle$) where:

- label $\in L$
- $\langle c_1, \ldots, c_n \rangle$ is a list of trees with labels in *L*

(possibly an empty list)



Vocabulary/basic notions



 $depth \le size \le max(arity)^{depth}$

- breadth-first enumeration:
- depth-first prefix enumeration:
- \bullet depth-first postfix enumeration:
- depth-first infix enumeration:

 $(\leftarrow \text{ only makes sense for binary trees})$

In java

• Typically encoded via a recursive class

```
class Tree<T>
  public T label;
  public ArrayList<Tree<T>> children;
  public static <T> Tree<T> Leaf(T x)
  {
      Tree<T> t = new Tree<T>();
      t.children = new ArrayList<Tree<T>>();
      t.label = x;
      return t;
  }
}
```

Tree<Integer> root = Leaf(10); root.children.add(Leaf(5)); root.children.add(Leaf(11)); root.children.add(Leaf(12)); root.children.get(1).add(Leaf(3)); What tree is this?

Tree example with memory representation

Tree<Integer> root = Leaf(10); root.children.add(Leaf(5)); root.children.add(Leaf(11)); root.children.add(Leaf(12)); root.children.get(1).add(Leaf(3));

A somewhat honest of the representation in memory



Non-trees?

• With linked lists, possible to create cycles

(and worse pathologies in the case of doubly-linked lists)

• Same here + an additional pitfall: **sharing**



Not necessarily:

• They can be seen as **graphs**

(Topic of next lecture)

• Can represent (potentially infinite) trees



Cons

• Cycles: no longer a finite well-defined notion of depth

 \Rightarrow a lot of tree algorithm no longer terminates like e.g. traversal

• Sharing: a single update modifies several spots in the unravelling

 $(\Rightarrow$ not an issue for **immutable** datastructures)

Cons

• Cycles: no longer a finite well-defined notion of depth

 \Rightarrow a lot of tree algorithm no longer terminates like e.g. traversal

• Sharing: a single update modifies several spots in the unravelling

 $(\Rightarrow$ not an issue for **immutable** datastructures)

Pros

• Cycles: can represent infinite trees in finite space

only regular trees, which may arguably admit more convenient representations

• Sharing: saves memory/can represent *directed acyclic graphs* (DAGs)

Cons

• Cycles: no longer a finite well-defined notion of depth

 \Rightarrow a lot of tree algorithm no longer terminates like e.g. traversal

• Sharing: a single update modifies several spots in the unravelling

 $(\Rightarrow$ not an issue for **immutable** datastructures)

Pros

• Cycles: can represent infinite trees in finite space

only regular trees, which may arguably admit more convenient representations

- Sharing: saves memory/can represent *directed acyclic graphs* (DAGs)
- Commonplace tacit assumption: No sharing/cycles in tree-like datastructure
- One just has to be extra clear about what they consider legal inputs/outputs

Cons

• Cycles: no longer a finite well-defined notion of depth

 \Rightarrow a lot of tree algorithm no longer terminates like e.g. traversal

• Sharing: a single update modifies several spots in the unravelling

 $(\Rightarrow$ not an issue for **immutable** datastructures)

Pros

• Cycles: can represent infinite trees in finite space

only regular trees, which may arguably admit more convenient representations

- Sharing: saves memory/can represent *directed acyclic graphs* (DAGs)
- Commonplace tacit assumption: No sharing/cycles in tree-like datastructure
- One just has to be extra clear about what they consider legal inputs/outputs
- For this lecture: no more sharing/cycles

Tree-like datastructures

• . . .

Often, you may want more/less flexibility than the generic tree datastructure

- Do you want to bound the arity of internal nodes?
- Do you care about the ordering of children?
- Do you care about empty spots for future children?
- Do you want more labels?
- Do you want different type of labels for e.g. leaves?

```
class AST {
   boolean isAnOperand;
   String repr;
   AST lhs;
   AST rhs;
}
```

 \rightarrow for most situations, similar issues/resolutions

Binary trees are those trees whose nodes have at most two children.

```
class BTree<T> {
  T label;
  BTree<T> leftChild;
  BTree<T> rightChild;
}
```

Conventions:

• leftChild and rightChild may be set to null

(for a leaf: both are **null**)

• it is possible that leftChild = null and rightChild != null

(we care about the order and "empty spots")

Binary search trees

Motivation: set with $O(\log(n))$ lookup and delete

. . .

```
Set(); // creates an empty set
void remove(T e); // removes one element
boolean contains(T e); // do I contain the element?
void add(T e); // add one element
Set union(Set s2); // adds all elements of s2
```

Op \Data	Array	List	ArrayList	TreeSet
Set(T)	$\mathcal{O}(1)$	$\mathcal{O}(1)$	$\mathcal{O}(1)$	$\mathcal{O}(1)$
remove	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(\log(n))$
contains	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(\log(n))$
add	$\mathcal{O}(n)$	$\mathcal{O}(1)$	$\mathcal{O}(n)$ $\mathcal{O}(1)$ amortized	$\mathcal{O}(\log(n))$
union	O(n+m)	$\mathcal{O}(1)$	$\mathcal{O}(n+m)$ $\mathcal{O}(m)$ amortized	$\mathcal{O}(m\log(n))$

A datastructure to represent set of numbers

Definition

A Binary Search Tree is a binary tree labeled by integers such that



$$\Rightarrow \qquad l \le x \le r$$



=

Look up an element boolean contains(int e)



Complexity of boolean contains(int e)?



Complexity of boolean contains(int e)?



 $\rightarrow \mathcal{O}(depth)$

Complexity of boolean contains(int e)?



 $\rightarrow \mathcal{O}(depth)$

Relation to the size of the set

- Best case: the tree is balanced \rightarrow depth = O(size)
- Worst case: one child everywhere \rightarrow depth = $\Omega(size)$

 \rightarrow Important concern: work on balanced trees

Insert an element void add(int e)



Insert an element void add(int e)



- Complexity: still O(depth)
- Issue: repeatedly inserting bigger and bigger elements can unbalance a tree

Try inserting $1, 2, 3, \ldots$ to Leaf(\emptyset)

Solutions (not covered in-depth here)

- Either try to do some probabilistic analysis and try to prove things are not that bad on average for a given use-case . . .
- ... or use fancier invariants to have classes of trees with depth = $O(\log(size))$
- Paradigmatic examples: red-black trees and AVLs



- Involved "repair" procedures to maintain the invariants after an insertion/deletion running in O(depth)
- Something like this is implemented for TreeSet

So now, you should be able to tell why this table is like this

Op \Data	Array	List	ArrayList	TreeSet
Set(T)	$\mathcal{O}(1)$	$\mathcal{O}(1)$	$\mathcal{O}(1)$	$\mathcal{O}(1)$
remove	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(\log(n))$
contains	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(n)$	$\mathcal{O}(\log(n))$
add	$\mathcal{O}(n)$	$\mathcal{O}(1)$	$\mathcal{O}(n)$ $\mathcal{O}(1)$ amortized	$\mathcal{O}(\log(n))$
union	O(n+m)	$\mathcal{O}(1)$	$\mathcal{O}(n+m)$ $\mathcal{O}(m)$ amortized	$\mathcal{O}(m\log(n))$

Priority queues, heaps and heapsort

Quick note

Motivation

Implement a priority queue with $O(\log(n))$ operations $+ \rightarrow$ a new in-place sorting algorithm in $O(n \log(n))$

The two operations supported by a priority queue

```
void enqueue(T e, int priority);
```

T dequeue();

This material is explained in some details in last week's lab!

- The last task was marked as challenge because it's about trees and we had not covered that last week
- But now you should try to do it!

What's a heap?

Definition

A min-heap is a binary tree such that

- The label of every node is smaller than its children's
- All of its levels are full, except possibly the last
- The last level is completely filled left-to-right



(for priority queues: numbers are priorities + extra label type T in nodes)

Examples/counter-examples



 \uparrow not a heap (unbalanced)

Inserting a new element and repairing in $O(\log(n))$



Deleting the root and repairing in $O(\log(n))$



 \uparrow valid heap

Representing trees as arrays

While the shape of a tree is good ot keep in mind, when they are of bounded arity and close to complete, it might be better to represent them as arrays



- Fast access due to $\mathcal{O}(1)$ lookup in arrays
- Downsides: *potentially* wasting memory and bounding a priori arities

(absent nodes = cells filled with **null**)

For heaps: that's a good representation!

Heap sort

The algorithm

- start with an empty heap
- insert all the elements in the collection you want sorted

 $\sum_{i=1}^{n} K \log(i) + K' = \mathcal{O}(n \log(n))$

• insert the value of the root at the back of your output and delete the root

 $\sum_{i=1}^{n} K'' \log(i) + K''' = \mathcal{O}(n \log(n))$

Heap sort

The algorithm

- start with an empty heap
- insert all the elements in the collection you want sorted

 $\sum_{i=1}^{n} K \log(i) + K' = \mathcal{O}(n \log(n))$

- insert the value of the root at the back of your output and delete the root $\sum_{i=1}^{n} K'' \log(i) + K''' = O(n \log(n))$
- Optimal asymptotic complexity for a comparison-based sort!
- Can be done *in-place* in an array wiht minor adjustement

O(n) space complexity

Bubble sort

- $\mathcal{O}(n^2)$
- In-place

Quick sort

- $\mathcal{O}(n^2)$, $\mathcal{O}(n \log(n))$ on average with randomized pivot
- Easily done in-place for arrays
- $O(n \log(n))$ with a smart pivot, but this breaks the in-place aspect of the algo.

Merge sort

- $\mathcal{O}(n \log(n))$, good for parallelization
- Not in-place for arrays
- A *stable* sort (does not disturb elements that are "equal")

Heap sort

- $\mathcal{O}(n\log(n))$
- In-place!

CountSort

• Not a comparison-based sort, can run in linear time **if working with numbers in a restricted range**.

That's all for today

See you in the lab to practice working with trees!

Next time we will introduces **graphs**.

